

Representations of Algebras and the Graph Isomorphism Problem

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Isomorphism problems can be translated to orbit problems.

Example: The Graph Isomorphism Problem

Γ_1, Γ_2 graphs with vertex set $\{1, 2, \dots, n\}$

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We'll get back to graphs later.

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$T = k\langle x_1, \dots, x_r \rangle / I$ associative algebra over k (with 1)

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Remark

$$A, B \text{ in same } G(k)\text{-orbit} \Leftrightarrow A, B \text{ in same } G(\bar{k})\text{-orbit}$$

Complexity of the Module Isomorphism Problem

Theorem (Chistov–Invanyos–Karpinski '97, Brooksbank–Luks '08)

There exists a T -module isomorphism test that requires only a polynomial number (in the dimension of the modules) of arithmetic operations in the field k .

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Isomorphism Test

v, w in the distinct $G(\bar{k})$ -orbits $\Leftrightarrow 1 \in I$

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If G is fixed, then one can test whether $1 \in I$ efficiently: the number of arithmetic operations in k required is polynomial in n and the degrees of the polynomials defining the representation V .

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One can use Buchberger's algorithm to test whether $1 \in I$, but this may not be efficient.

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(k , G , V as before)

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- 4 If v, w are isomorphic in $\mathcal{C}_d(V)$ for all $d \geq 1$, then v and w are in the same $G(\bar{k})$ -orbit

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- 4 If v, w are isomorphic in $\mathcal{C}_d(V)$ for all $d \geq 1$, then v and w are in the same $G(\bar{k})$ -orbit
- 5 There exists an efficient algorithm to determine if v and w are isomorphic in $\mathcal{C}_d(V)$

Truncated Ideals

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$$(S)_d = \sum_{e=0}^d (S \cap R_e) R_{d-e}.$$

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The sequence

$$(S)_d \subseteq ((S)_d)_d \subseteq (((S)_d)_d)_d \subseteq \dots$$

stabilizes to a d -truncated ideal which will be denoted by $((S))_d$.

A nice Filtration for $k[G]$

Let G be a linear algebraic group over k
 $G \times G$ acts on $R = k[G]$ by

$$((g, h) \cdot f)(u) = f(g^{-1}uh), \quad f \in R, g, h, u \in G$$

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Define a filtration by $R = \bigcup_d R_d$, where $R_d = W^d$

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The Algebra Structure for R_d^*

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Then $\Delta(R_d) \subseteq R_d \otimes R_d$

So R_d^* is an associative algebra

The category $\mathcal{C}_d(V)$

Objects

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gives a system of polynomials $S(X_1, X_2) \subset R_d$

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Morphisms

We define $\text{Hom}_d(X_1, X_2) = (R_d/I_d(X_1, X_2))^*$. The bilinear map $\text{Hom}_d(X_1, X_2) \times \text{Hom}_d(X_2, X_3) \rightarrow \text{Hom}_d(X_1, X_3)$ is the restriction of the multiplication $R_d^* \times R_d^* \rightarrow R_d^*$.

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- We can test whether two T -modules are isomorphic efficiently, and if T and $\text{Hom}_d(X_2, X_1)$ are isomorphic, we can compute an isomorphism $\varphi : \text{Hom}_d(X_1, X_1) \rightarrow \text{Hom}_d(X_2, X_1)$

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- Let $f = \varphi(\text{id})$. Then X_1 and X_2 are isomorphic if and only if f is an isomorphism. This is easy to test.

The Graph Isomorphism Problem

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Another well-known algorithm is the d -dimensional Weisfeiler-Lehman algorithm (60's).

The d -dimensional Weisfeiler-Lehman algorithm

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The stable coloring is invariant under $\text{Aut}(X)$. If Γ_1, Γ_2 are distinct graphs, then we can take Γ as the disjoint union. If a vertex of Γ_1 get a color that does not appear in Γ_2 , then Γ_1 and Γ_2 are not isomorphic.

We can think of a graph $\Gamma = (X, E)$ as a structure, and to this structure we can associate the first order logic. In the d -variable language \mathbf{L}_d , we only allow d variables to be used (but one may re-use variables)

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For example:

$$\varphi(x_1, x_2) = \exists x_3 [\exists x_2 E(x_1, x_2) \wedge E(x_2, x_3)] \wedge E(x_3, x_2)$$

says “ x_1 and x_2 are connected by a path of length 3”. The formula uses 3 variables (x_2 has been re-used).

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For example

$$\psi(x_1) = \exists_{37} x_2 \varphi(x_1, x_2)$$

means “ there are exactly 37 vertices that can be connected to x_1 by a path of length 3” .

Theorem

The d -dimensional Weisfeiler-Lehman algorithm can distinguish two graphs Γ_1, Γ_2 if and only if there exists a closed formula ψ in the $(d + 1)$ -variable logic with counting such that ψ is true for Γ_1 but not for Γ_2 .

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Theorem (CFI)

For every d there exists two non-isomorphic graphs Γ_1 and Γ_2 such that for every formula ψ in \mathbf{C}_{d+1} , ψ is true for Γ_1 if and only if ψ is true for Γ_2 . So the d -dimensional Weisfeiler-Lehman algorithm cannot distinguish Γ_1 and Γ_2 .

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Theorem

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For fixed d , isomorphisms in $\mathcal{C}_d(V)$ can be checked using a polynomial number of arithmetic operations in k . If $k = \mathbb{F}_p$ and $\log p = O(n)$ then isomorphism can be checked in polynomial time.

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So our algorithm is at least as powerful as the Weisfeiler-Lehman algorithm.

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If $k = \mathbb{F}_2$ then A_1, A_2 are *not* isomorphic in $\mathcal{C}_3(V)$.

Distinguishing the CFI graphs in polynomial time

Suppose that Γ_1, Γ_2 is a pair of non-isomorphic graphs in the Cai-Fürer-Immerman family.

Theorem

If $k = \mathbb{F}_2$ then A_1, A_2 are *not* isomorphic in $\mathcal{C}_3(V)$.

So using our algorithm distinguishes these graphs in polynomial time, but the Weisfeiler-Lehman algorithm cannot distinguish these graphs in polynomial time.

Why is our algorithm more powerful?

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It is hard to say “the rank of the adjacency matrix (over the field \mathbb{F}_p) of Γ has rank r . One cannot express such a sentence in \mathbf{C}_d for small d .

Our algorithm captures a “logic” that is more powerful. For $d = 3$ one can already express that the adjacency matrix has rank r .

The CFI graphs can easily be distinguished, because their adjacency matrices have canonical submatrices with distinct ranks (when working over \mathbb{F}_2).

Can our algorithm distinguish the CFI graphs in polynomial time if we work over fields of characteristic $\neq 2$?

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(Wishful thinking)

Can our algorithm distinguish all graphs in polynomial time?